

High-velocity regime in Kelvin wakes

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First year PhD Seminar



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OUTLINE



- What is the **Kelvin wake**?

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- Derivation of **Kelvin angle**

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- Conclusions

WHAT IS THE KELVIN WAKE?



- Standard fluid dynamics (Lord Kelvin 1887) predicts that the **wake angle** formed by a moving object with constant velocity in still, deep water is **$\arcsin(1/3)$** .



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- This result is **independent** of the **shape** and **velocity** of the object.
- This is the angle formed by **ducks** in a (deep-enough) pond, **moving boats** far from the coast etc.



DERIVATION OF KELVIN ANGLE



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- The equations governing the dynamics are:

$$\partial_t \rho + (\mathbf{v} \nabla) \rho = -\rho (\nabla \cdot \mathbf{v})$$

Conservation of mass

$$\partial_t \rho \mathbf{v} + \nabla (\mathbf{v} \rho \mathbf{v}) = -\nabla P + \mathbf{f}$$

Conservation of momentum

DERIVATION OF KELVIN ANGLE



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- And assuming stationarity (identical to the Mach cone):

$$U \cos \theta(k) = c_\varphi(k) = \sqrt{g/k}.$$

DERIVATION OF KELVIN ANGLE



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DERIVATION OF KELVIN ANGLE



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DERIVATION OF KELVIN ANGLE



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- This implies: $\lambda(\theta) = \frac{2\pi U^2 \cos^2 \theta}{g}$

DERIVATION OF KELVIN ANGLE



- Transforming to the boat reference frame and applying stationarity (boat velocity drops!):

$$\frac{y}{x} = -\frac{\cos \theta \sin \theta}{1 + \sin^2 \theta} = \frac{y}{x}(\theta)$$

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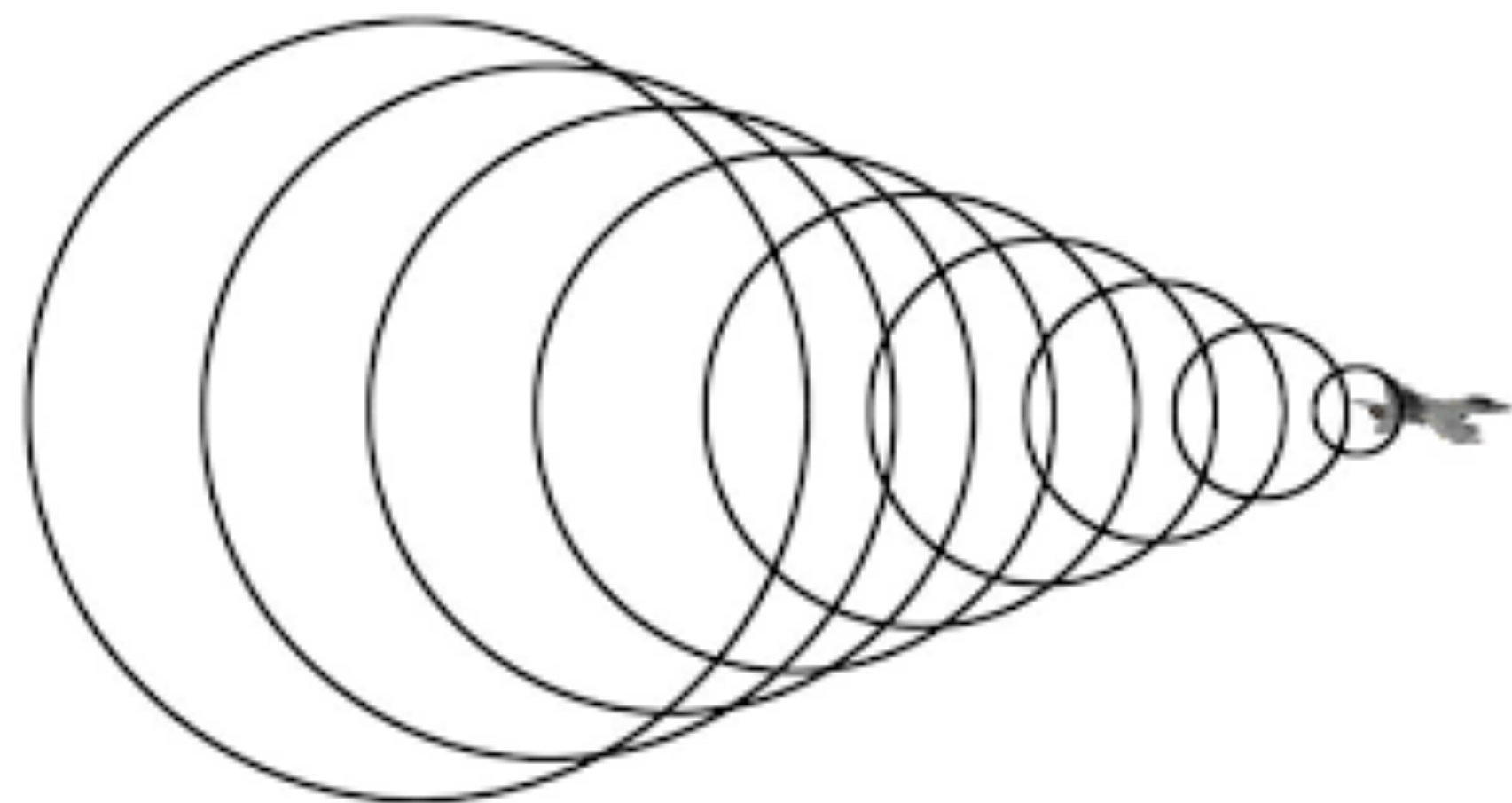
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- Thus waves are bounded within the envelope defined by: $\frac{y}{x} \Big|_{Max} = 2^{-3/2}$
- Which corresponds to an angle of ~ 19.5 deg



SOME (GENERAL?) INTUITION

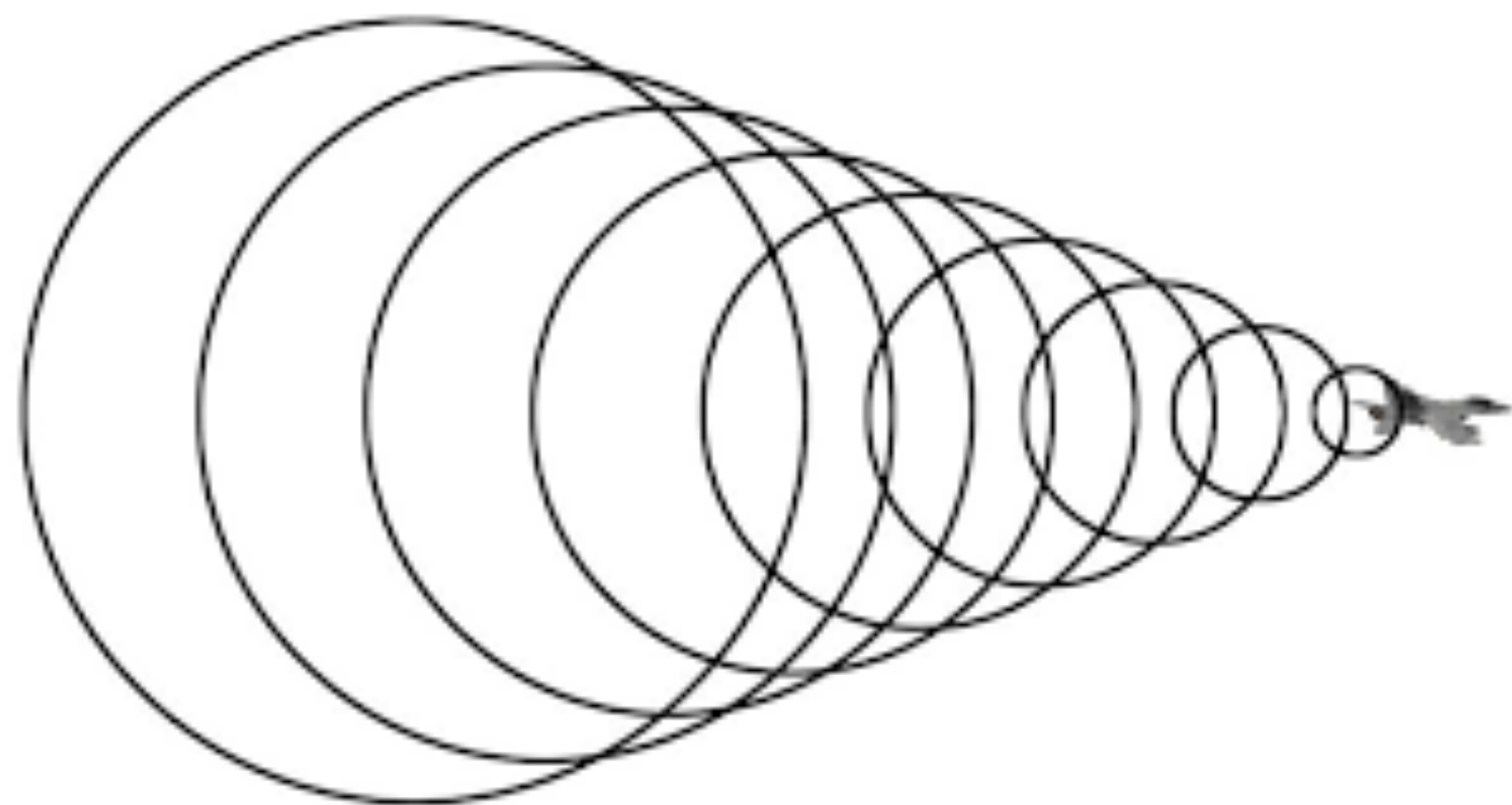
- But **supersonic physics** (together with relativity, electrodynamics,...) give us a different intuition, i.e. the **angle** should **shrink** for **high** boat **speed**.



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$$\cos(\theta) = \frac{v_s}{U}$$

- Is this intuition correct? (the regime is very different, here we are in the presence of an incompressible fluid with gravity as restoring force and a **non-linear dispersion relation**)

SATELLITE DATA ON MOVING BOATS



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- How can someone **experimentally verify** this result? With a drone, a ML pattern recognition algorithm and a (powerful enough) ship.

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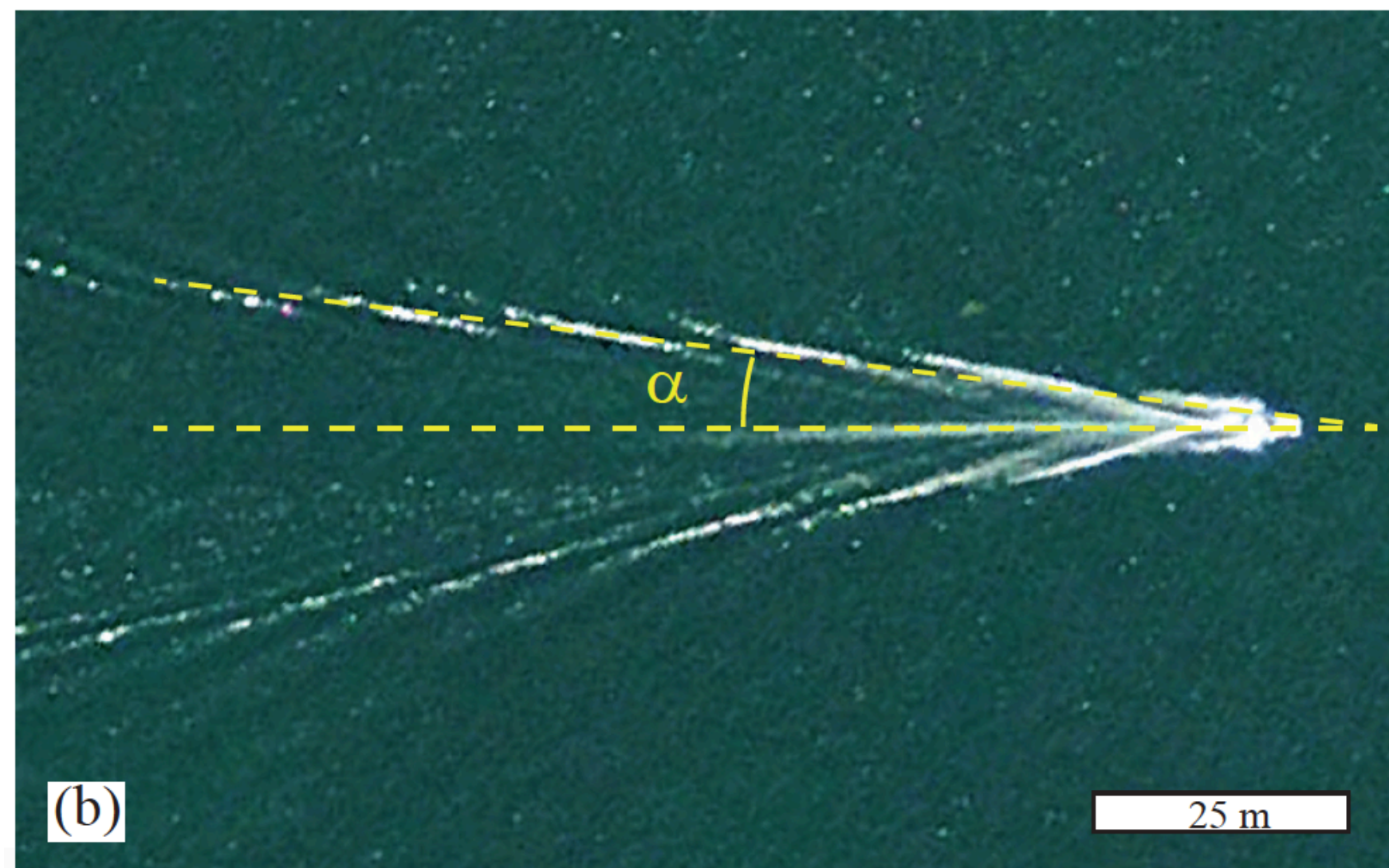
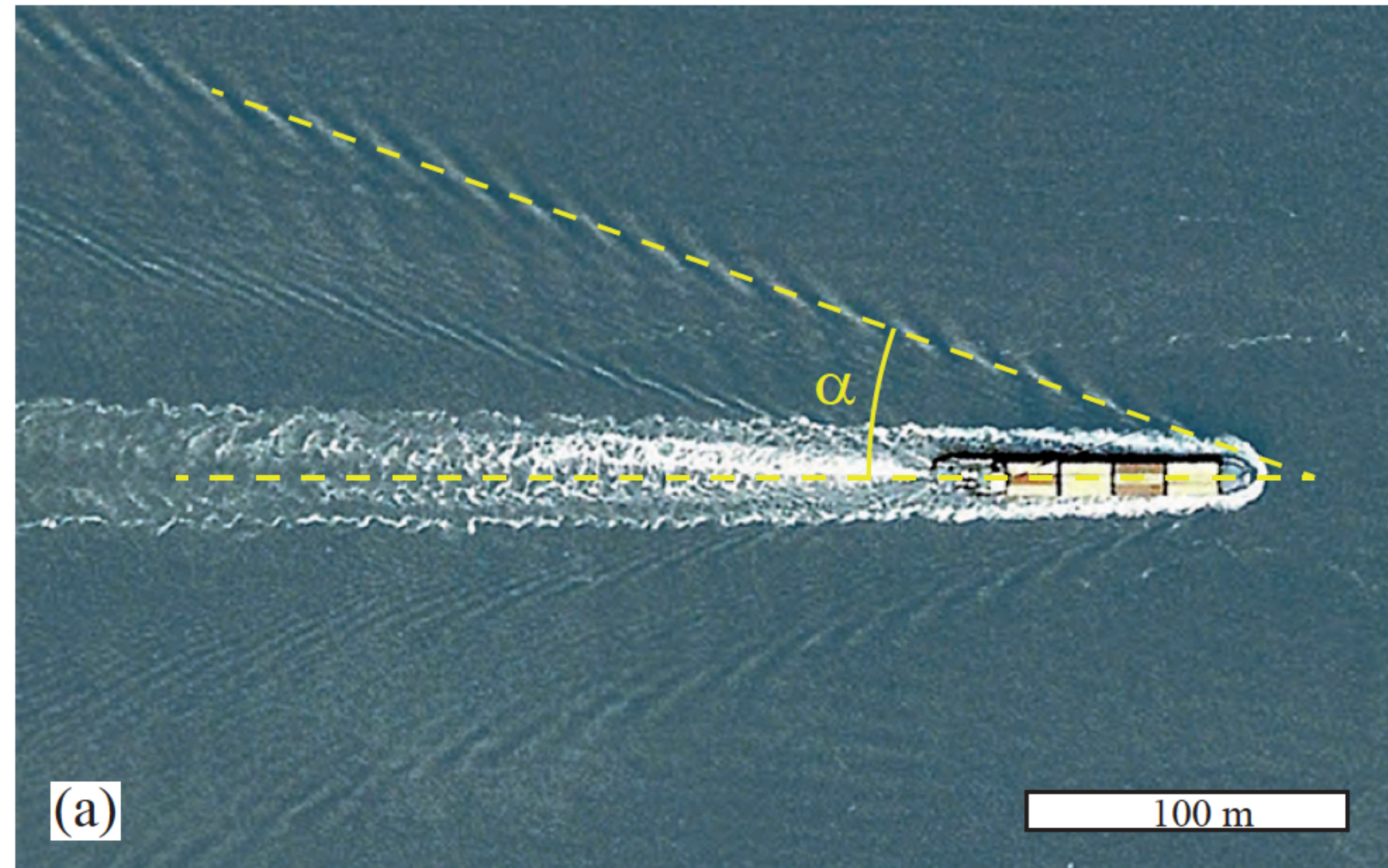
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- How can someone **experimentally verify** this result? With a drone, a ML pattern recognition algorithm and a (powerful enough) ship.
- In absence of dedicated funding **Rabaud and Moisy** relied on the Google Earth (GE) database.
- Using GE calibration the **wake angle**, together with **size** and **speed** of the ship can be determined (after correcting for parallax effects).
- The **speed** come from the wavelength measurement and $\lambda(\theta) = \frac{2\pi U^2 \cos^2 \theta}{g}$:
main source of error.

SATELLITE DATA ON MOVING BOATS



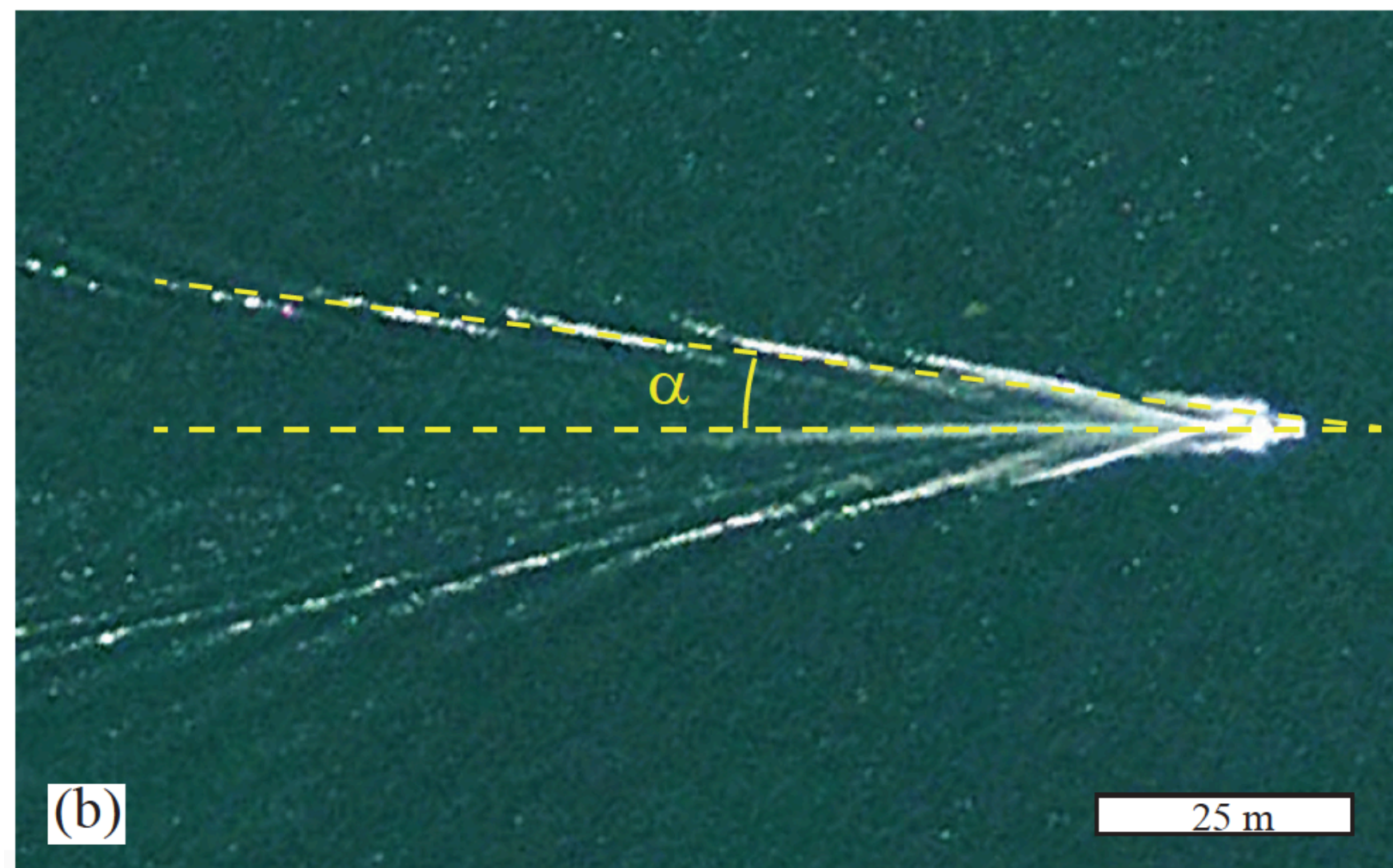
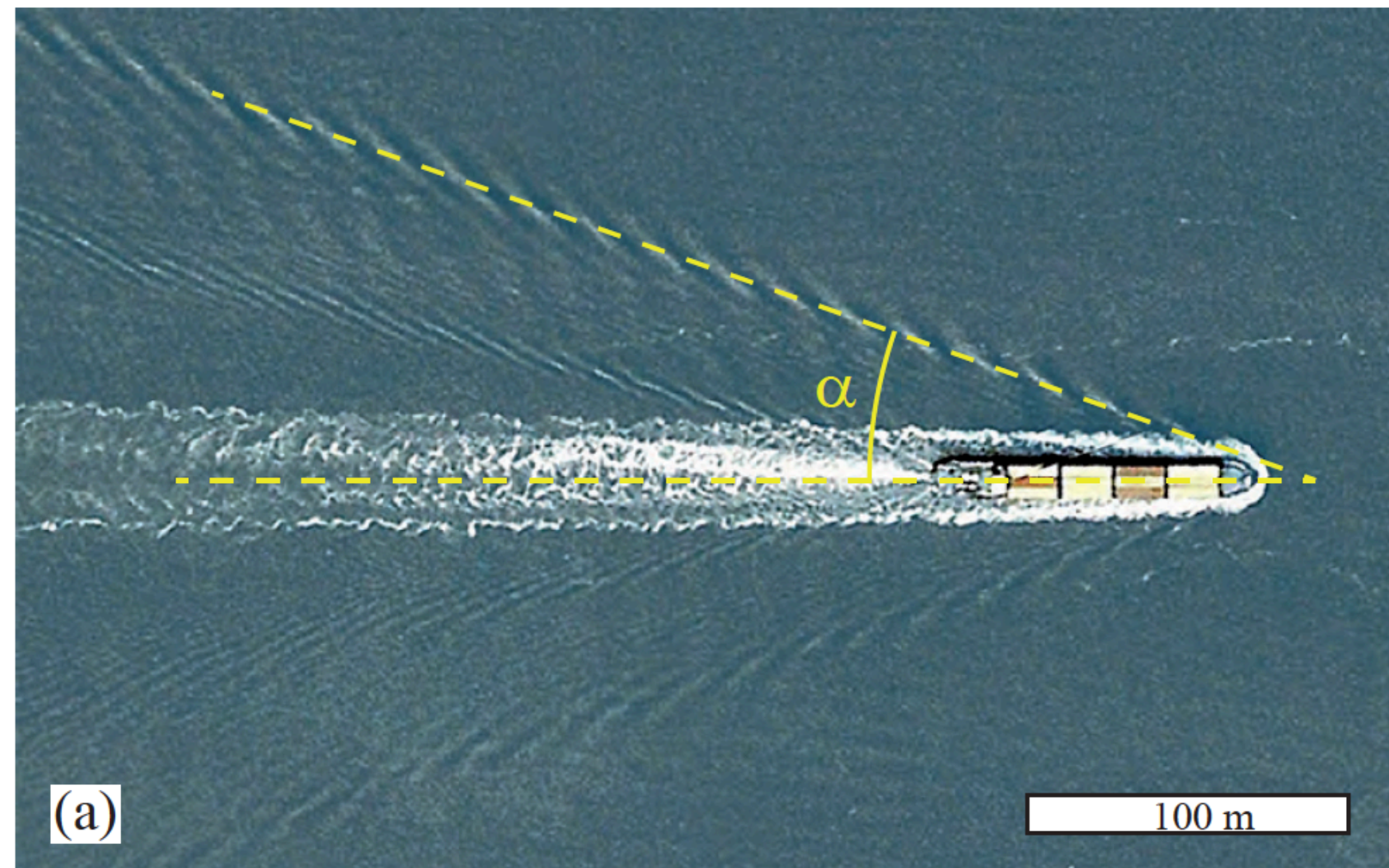
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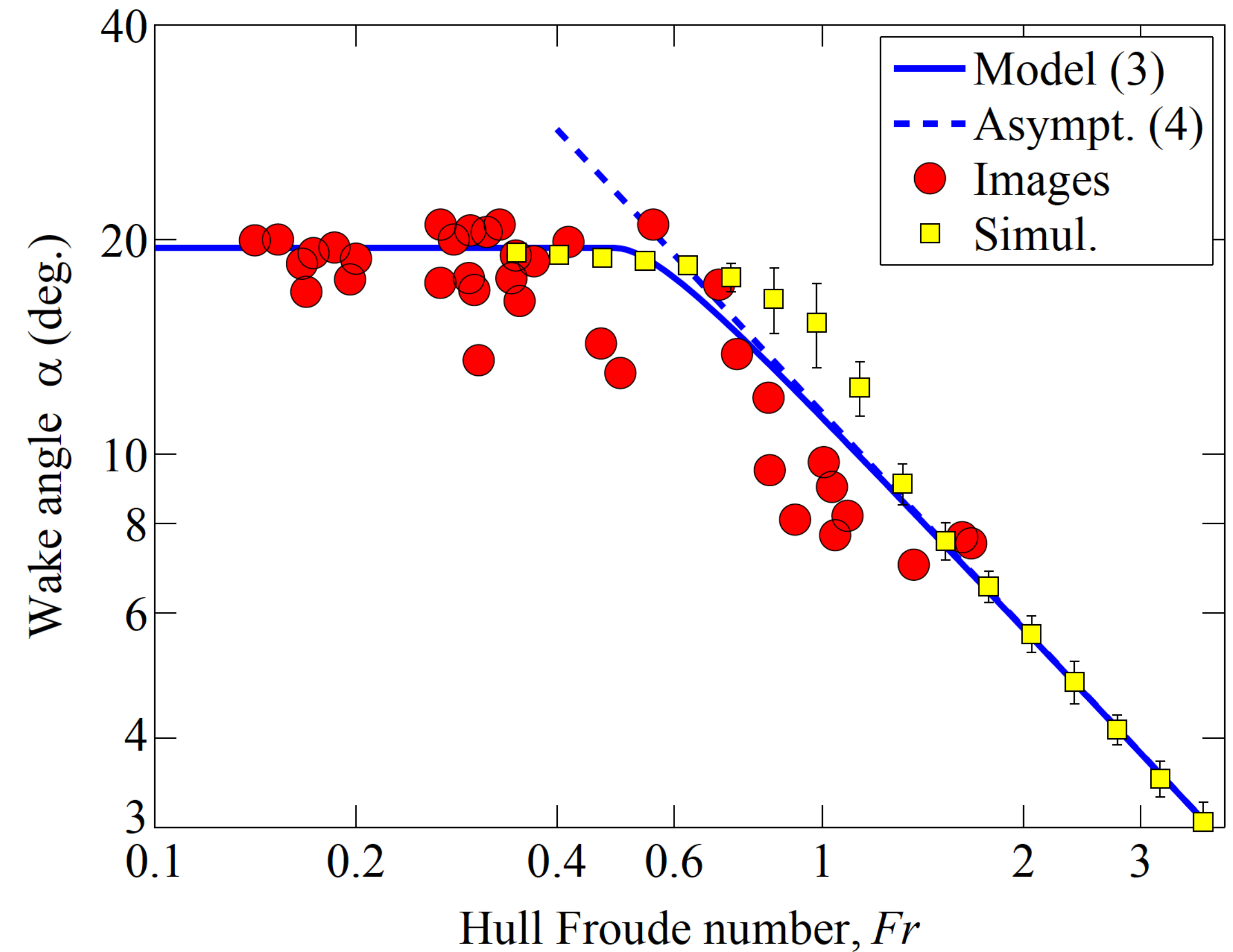
SATELLITE DATA ON MOVING BOATS



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Clear transition at large velocities!



$$Fr = U / \sqrt{gL}$$

TRANSITION TO HIGH-VELOCITY REGIME



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- Where is the **Kelvin model failing**? (Heuristic explanation)
- In performing the maximization, it was assumed that **all wavelength** could be **equally excited**.
- Rabaud and Moisy proposed a model for which a boat of size L cannot excite wavelength $\lambda \gg L$.
- According to this model a **cutoff** must be imposed on the previous maximization.

TRANSITION TO HIGH-VELOCITY REGIME



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- This cutoff leads to:

$$\alpha = \tan^{-1}(1/\sqrt{8}) \simeq 19.47^\circ, \quad Fr \leq Fr_c$$

$$\alpha = \tan^{-1} \frac{\sqrt{2\pi Fr^2 - 1}}{4\pi Fr^2 - 1}, \quad Fr \geq Fr_c,$$

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- And in the high-velocity regime to:

$$\alpha \approx \frac{1}{2\sqrt{2\pi Fr}}$$

TRANSITION TO HIGH-VELOCITY REGIME



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- Simulations performed using a moving gaussian pressure distribution show:

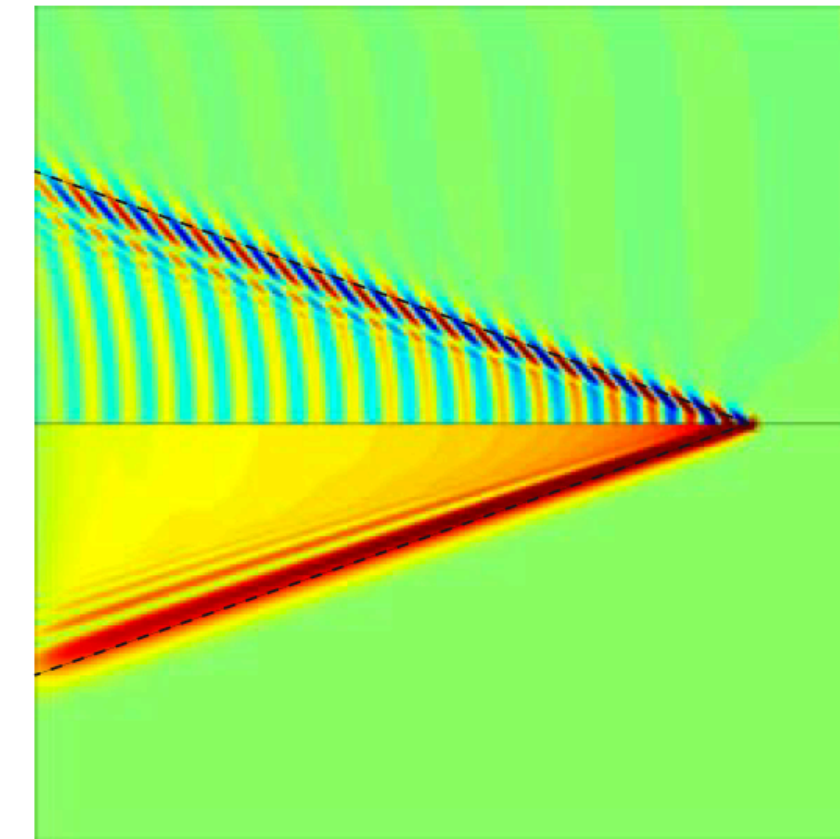
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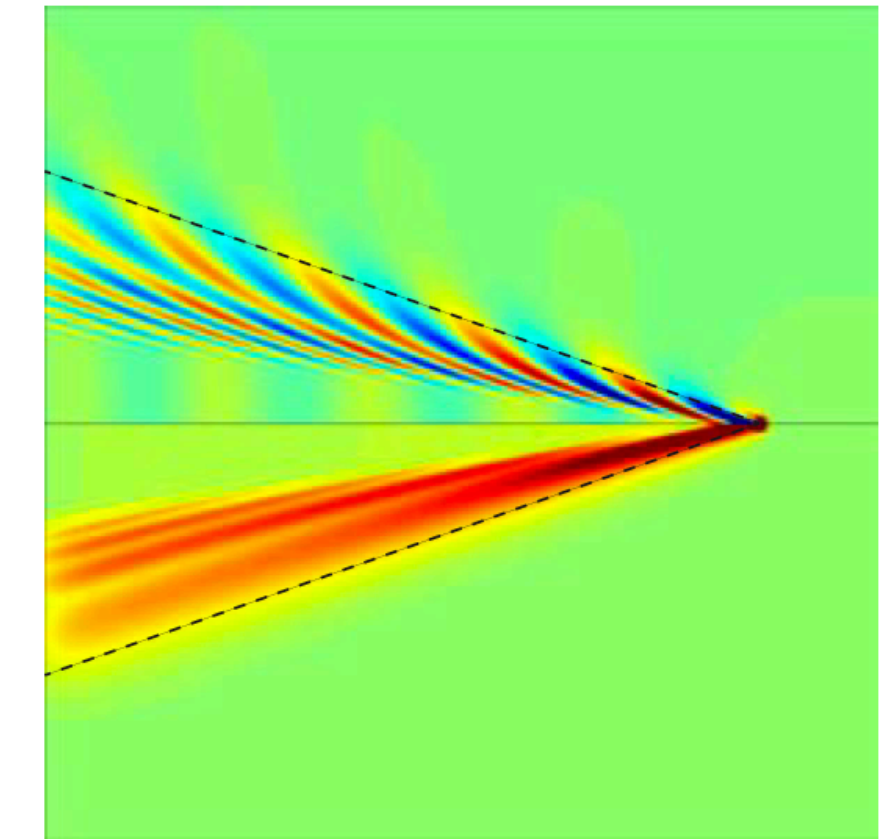
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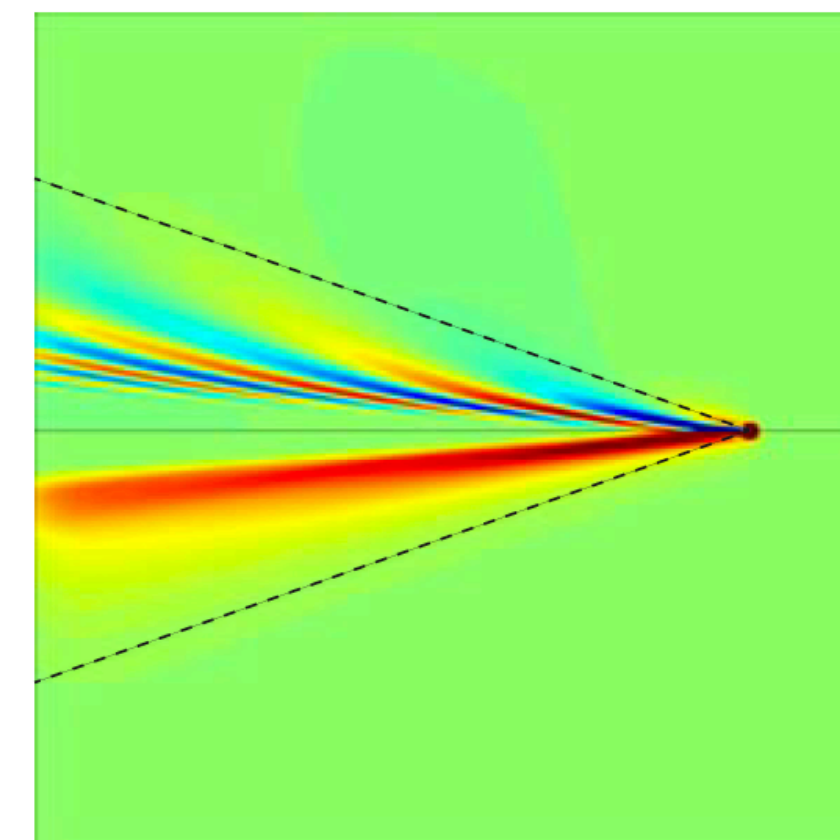
(a) $Fr = 0.5$, $\alpha = 18.9^\circ$



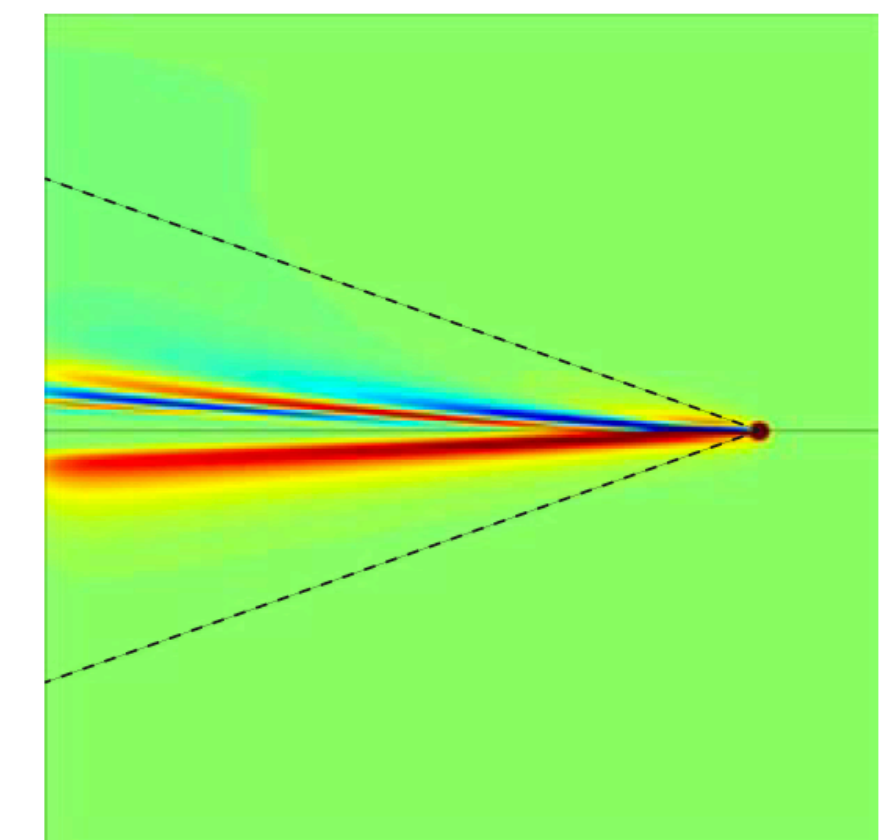
(b) $Fr = 1$, $\alpha = 15.9^\circ$



(c) $Fr = 2$, $\alpha = 5.8^\circ$



(d) $Fr = 4$, $\alpha = 2.9^\circ$



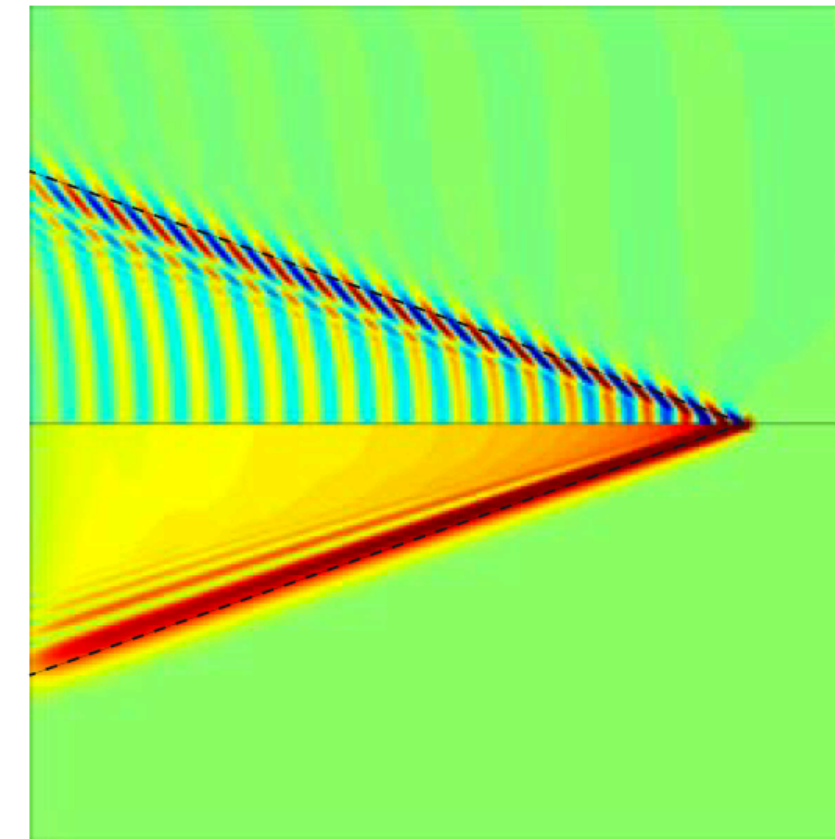
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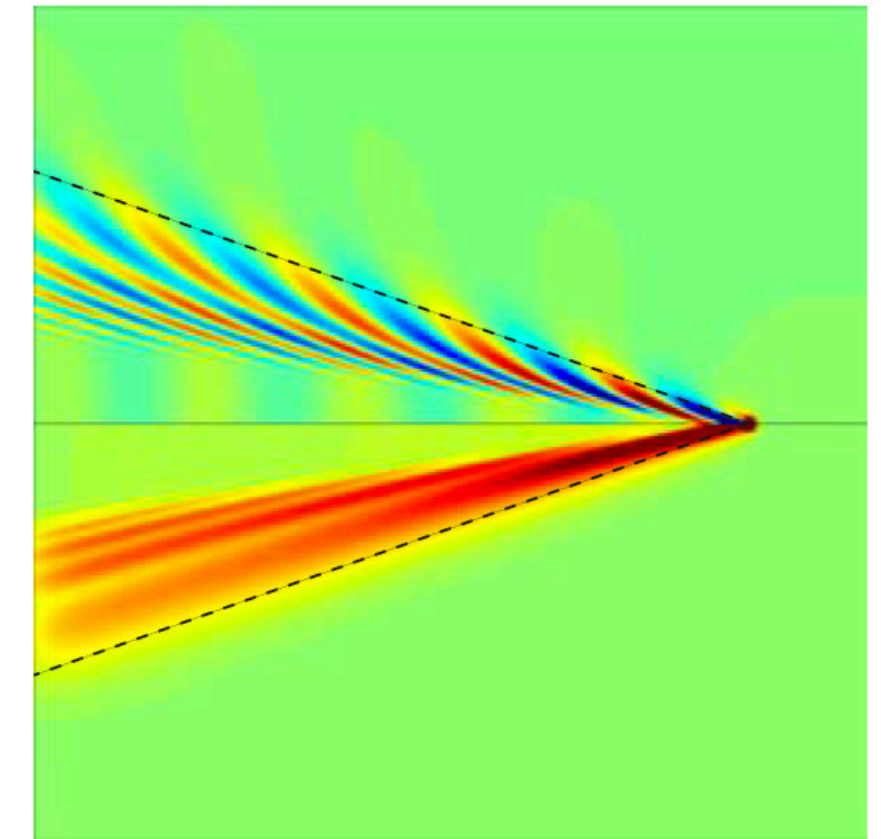
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- In full agreement with the presence of both a **Kelvin-like** and a **Mach-like regime**.

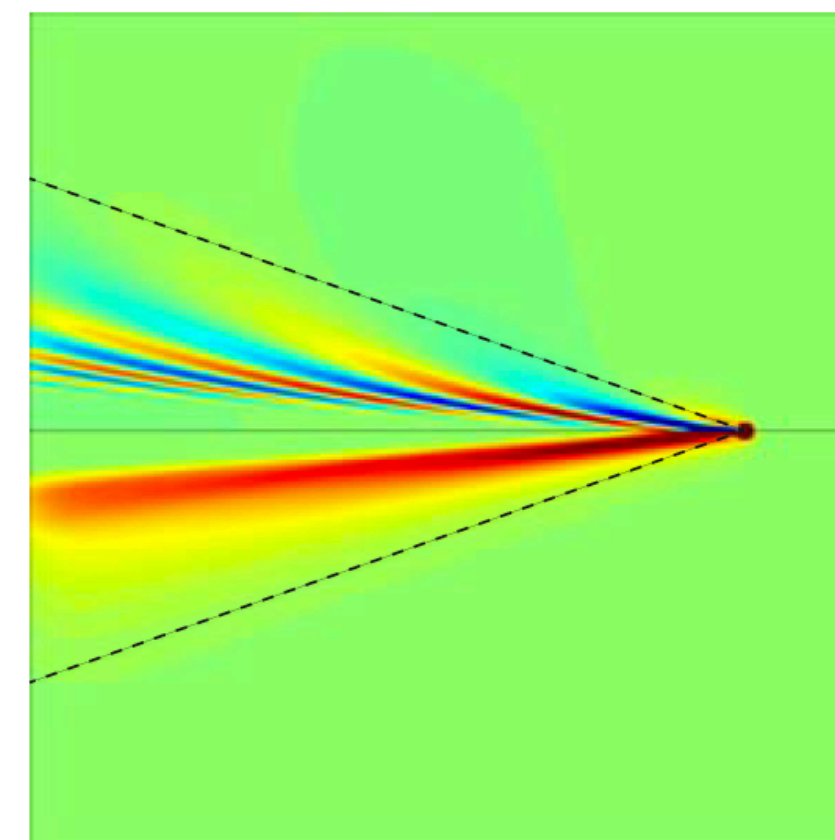
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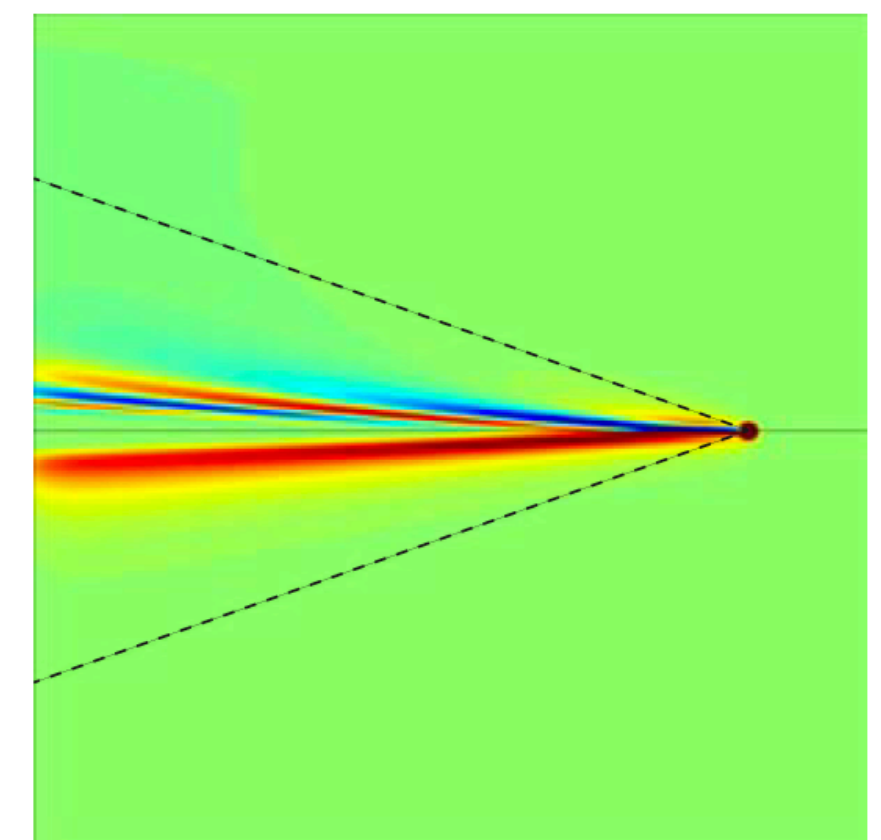
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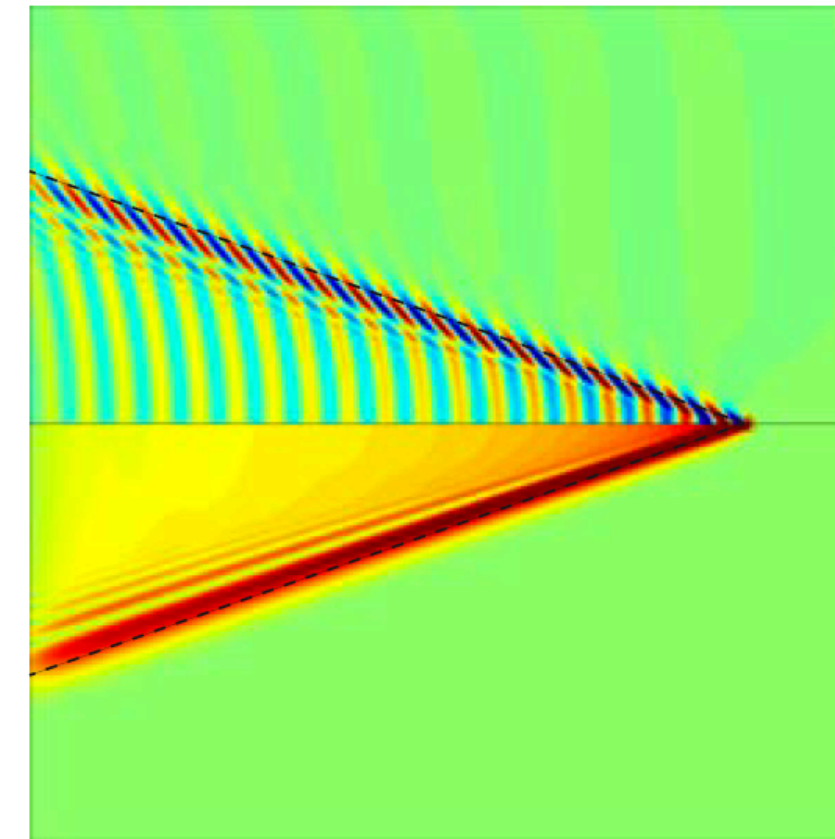
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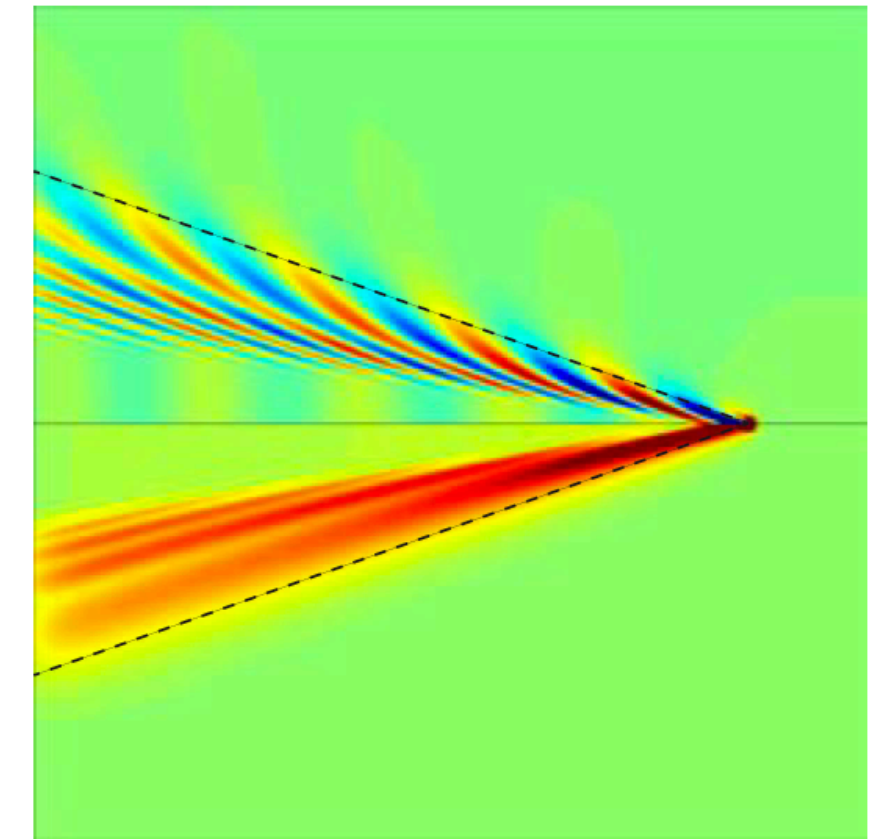
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- In full agreement with the presence of both a **Kelvin-like** and a **Mach-like regime**.
- **Supersonic behaviour** reproduced from a pure **dispersive effect**!

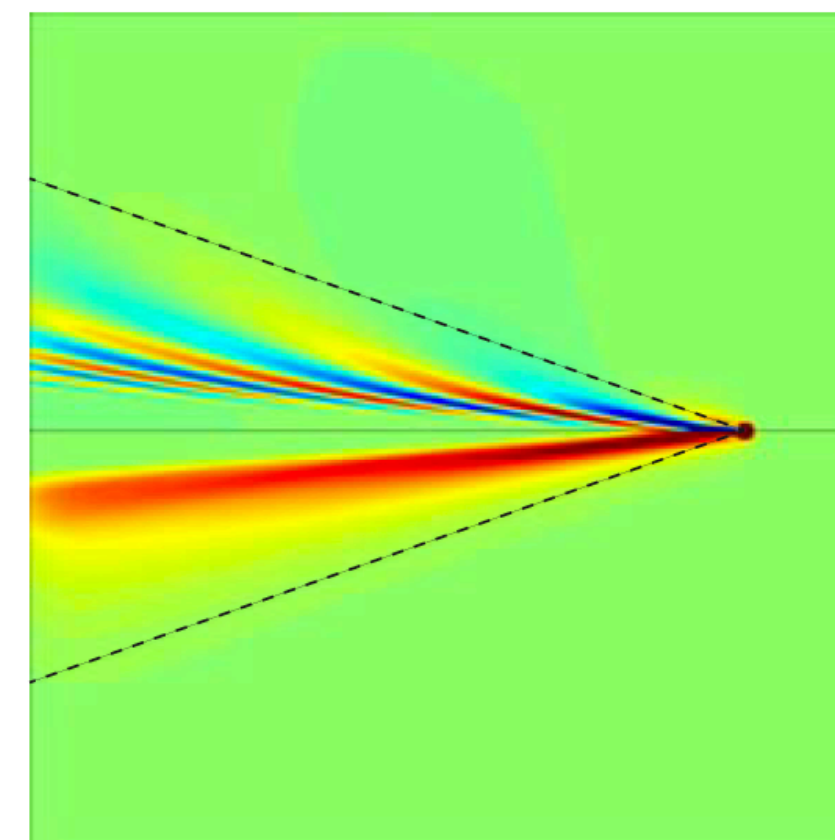
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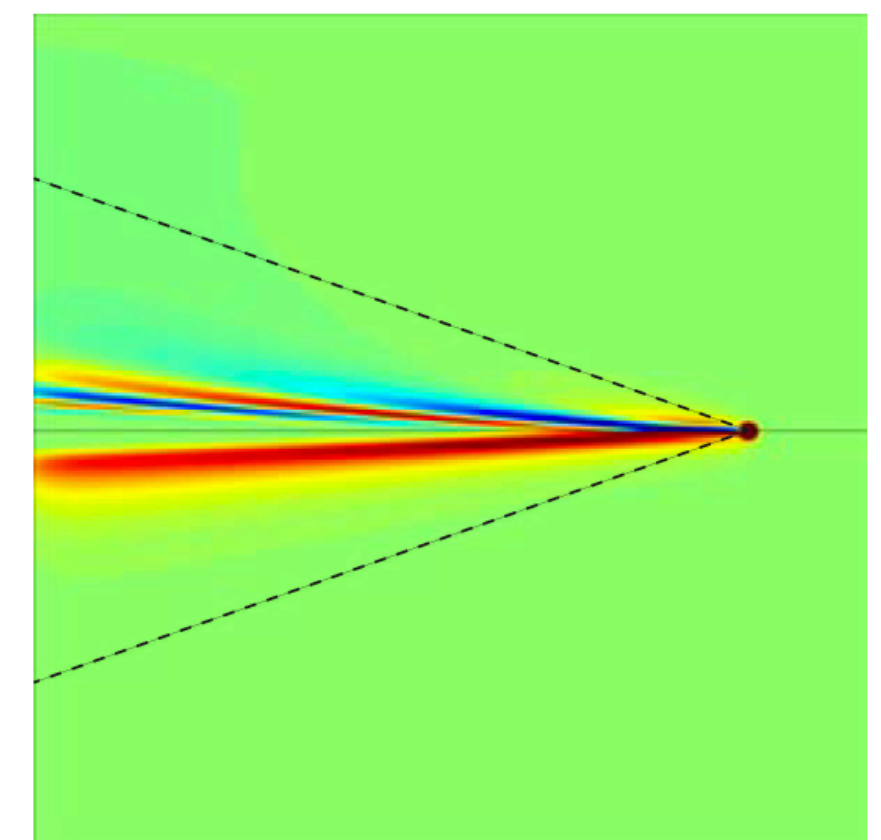
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TRANSITION TO HIGH-VELOCITY REGIME



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TRANSITION TO HIGH-VELOCITY REGIME



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- Darmon+ proved that there is **no need for such assumption**.
- They reproduced the $\frac{1}{U}$ behaviour through a **pure analytic treatment**:

$$\zeta(x, y) = - \lim_{\varepsilon \rightarrow 0} \iint \frac{dk d\theta}{4\pi^2 \rho} \frac{\hat{p}(k, \theta) e^{-ik(\cos \theta x - \sin \theta y)}}{c(k)^2 - V^2 \cos^2 \theta + 2i\varepsilon V \cos \theta / k}$$

TRANSITION TO HIGH-VELOCITY REGIME



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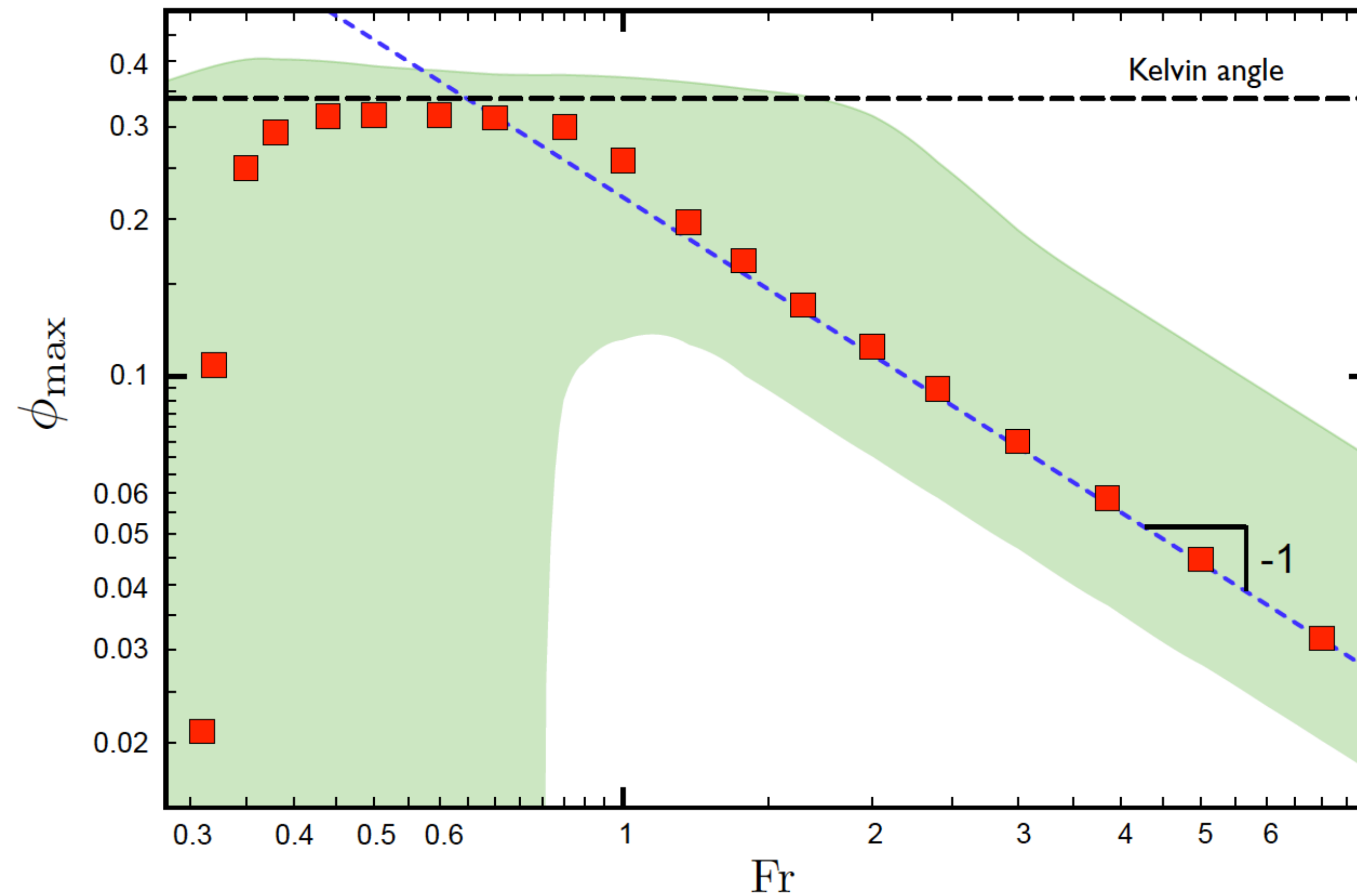
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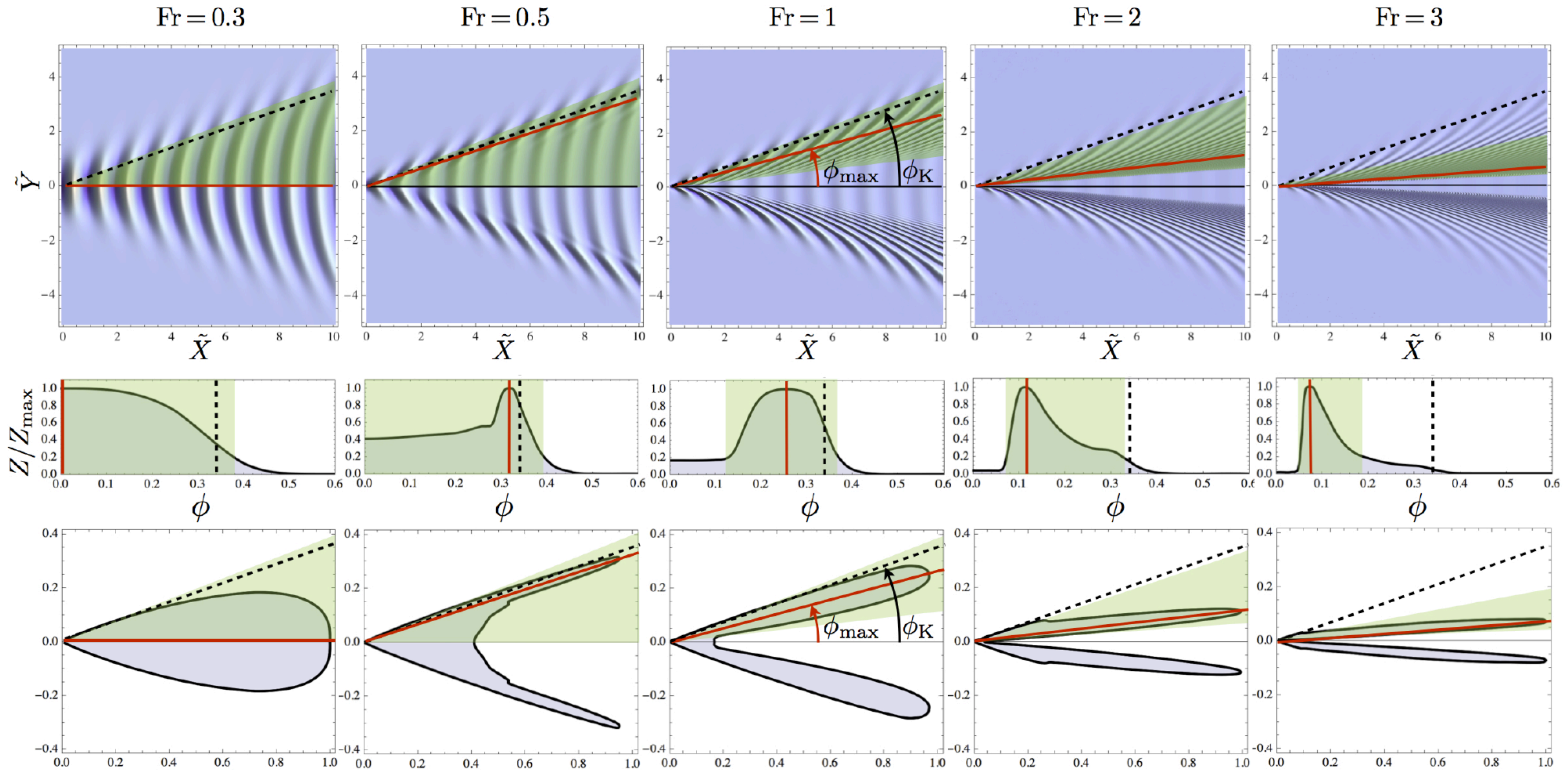
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TRANSITION TO HIGH-VELOCITY REGIME



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TRANSITION TO HIGH-VELOCITY REGIME



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- The wake envelope is **always bounded** from above by **Kelvin angle**, but the waves corresponding to such angle are **not** the one with the **largest amplitude!**
- The angle corresponding to the largest amplitude instead follows the U^{-1} prediction (**Supersonic behaviour** reproduced from a pure dispersive effect!)

CONCLUSIONS



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- At **low velocities** (compared to a typical velocity introduced by gravity and finite-size effects) the standard result (**19.5 deg**) is recovered
- At **high velocity** a **Mach-like regime** kicks in and a $\frac{1}{U}$ behaviour is recovered
- Nonetheless the Kelvin angle prediction has been shown to be robust even in the high velocity regime, although not relative to the waves at peak amplitude



That's all Folks!